IN SITU SURVEYING OF SATURN'S RINGS

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What are ANTS and SARA?

ANTS: Autonomous NanoTechnology Swarm

- Inspired by success of social insect colonies where

 Within their specialties, individuals outperform generalists
- With sufficiently efficient social interaction and coordination, groups of specialists outperform groups of generalists.

 A Generic Mission Architecture based on:
- Spatially distributed spacecraft
- Autonomous, redundant components with high plasticity Hierarchical (multilevel, dense heterarchy) organization

- ANTS application to survey dense neteratory) organization

 ANTS application to survey dense, dynamic, high G population

 1000 spacecraft swarm

 10 types of 'specialists' with common spacecraft bus

 10 subswarms, ~100 spacecraft each, ~10 each specialist

 - Hybrid propulsion for operation in two regimes:

 - Solar Sail Transport 'Hive Ship' cruise to outer solar system
 Nuclear Propulsion for individual craft navigate around rings
 Small nuclear batteries for 100's of milliwatt power requirements
 Primary objective is in situ exploration of Saturn's Rings to
 understand formation and origin of planetary systems

SARA Estimated Mission Parameters and Requirements

Mission Date

2030 Mission Duration 10 years

Mission Location

1-3 kg

Spacecraft Mass Power System Mass

Saturn's Rings 0.25-1.0 kg

Power Required

100-300 milliwatts

Storage Life in Space

10 years

3-axis stable

Spacecraft Attitude Operations:

Deep space operations far from Earth & Sun

1 year optimal science operations covering millions of particles

Full suite of science instruments deployed in and around ring plane

Concurrent operations at hundreds of ring particles

No single point of failure; robust to minor faults/catastrophic failures Optimal operations in spite of mission attrition

PAM Concept Development: Current Issues

- The SARA mission concept is an in situ survey of a Saturn's dynamic ring particle population.

 Such a survey can't be obtained from earth-based observations.

 - Incremental improvements in instrumentation and computer technologies will continue to allow the analysis and dynamic modeling of ring bulk properties from Earth based observations.

 - Current outer planet mission strategies do not allow individual ring particles to be studied.

 An in situ survey of Saturn's Rings is a challenge unachievable by conventional (direct control of single spacecraft from Earth) or even evolutionary (direct control of multiple spacecraft from Earth surrogate) mission designs.
 - Understanding the origin and dynamics of satellite system formation on Saturn and its relationship to planetary system origin and formation demands correlation of compositional data which can only be obtained by an in situ sampling mission.



Science Objectives for Saturn's Rings

Current Questions

SARA Addressing Strategy

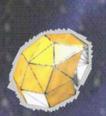
The high density distribution of particles on the scale of particles size, combines with the high intensity gravity and magnetic field environment to produce dynamic plasmas. What are the de tails of this process?

Plasma, particle, wave, and field detectors will probably fly just above or below the ring plane to observe the result of particle

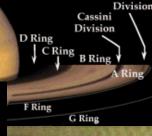
Although composition is essentially cometary with high volatile abundances, great variations could remain in the dust/gas ratio and the composition of dust component for individual particles. What is the nature of these variations?

Imagers and spectrometers will need to develop a strategy for serial rendezvous with individual particles through the ring.

Encke







PAM Concept Development Methodology Develop Conceptual Model for Behavior

- - Neural Basis Function based on bilevel intelligence Combines capability for autonomous and collective
 - Model applies at all levels: component, subsystem, spacecraft, subswarm
 - Individual operational components connect to each other through specially designed interface
- Develop scaled physical models and simulations to illustrate modularity, configurability, scalability

 Hive ship structure, packaging, and deployment

 Individual spacecraft structure, deployment from hive

 Trade study of low expendable propulsion options

 Formulate requirements and operational scenarios
- driven by high density, dynamic spacecraft size targets with highly volatile composition in high G environment.

PAM Concept Development: Autonomous Assembly

- Autonomous assembly and deployment minimizes resource requirements, including bandwidth and human labor. Components are composed of carbon nanotubule strands (tethers) or fibers (surfaces) reversibly deployable and stowable from MEMS or NEMS nodes, allowing for orders of magnitude decrease in packaging or stowing volume.

 - A tetrahedron of NEMS nodes forms the basic 'building block'.

 Assembly is based on creating 2D layers of interconnected NEMS nodes in two patterns.
 - Specialized subsystem nodes can be added to any layer.

 - 2 layers of different pattern form the sail support.

 A 3 layer sandwich, with different pattern layer in the middle, forms the subsystem platform.

 Subsystems are tethered together.

 After assembly, spacecraft are stowed, spooled back into nodes.
 - 1000 autonomous 10 centimeter, 1 kg boxes would stow into a 1 meter, 1000 kg cube.

